

ON THE ASYMPTOTIC LINEAR CONVERGENCE OF GRADIENT DESCENT FOR NON-SYMMETRIC MATRIX COMPLETION



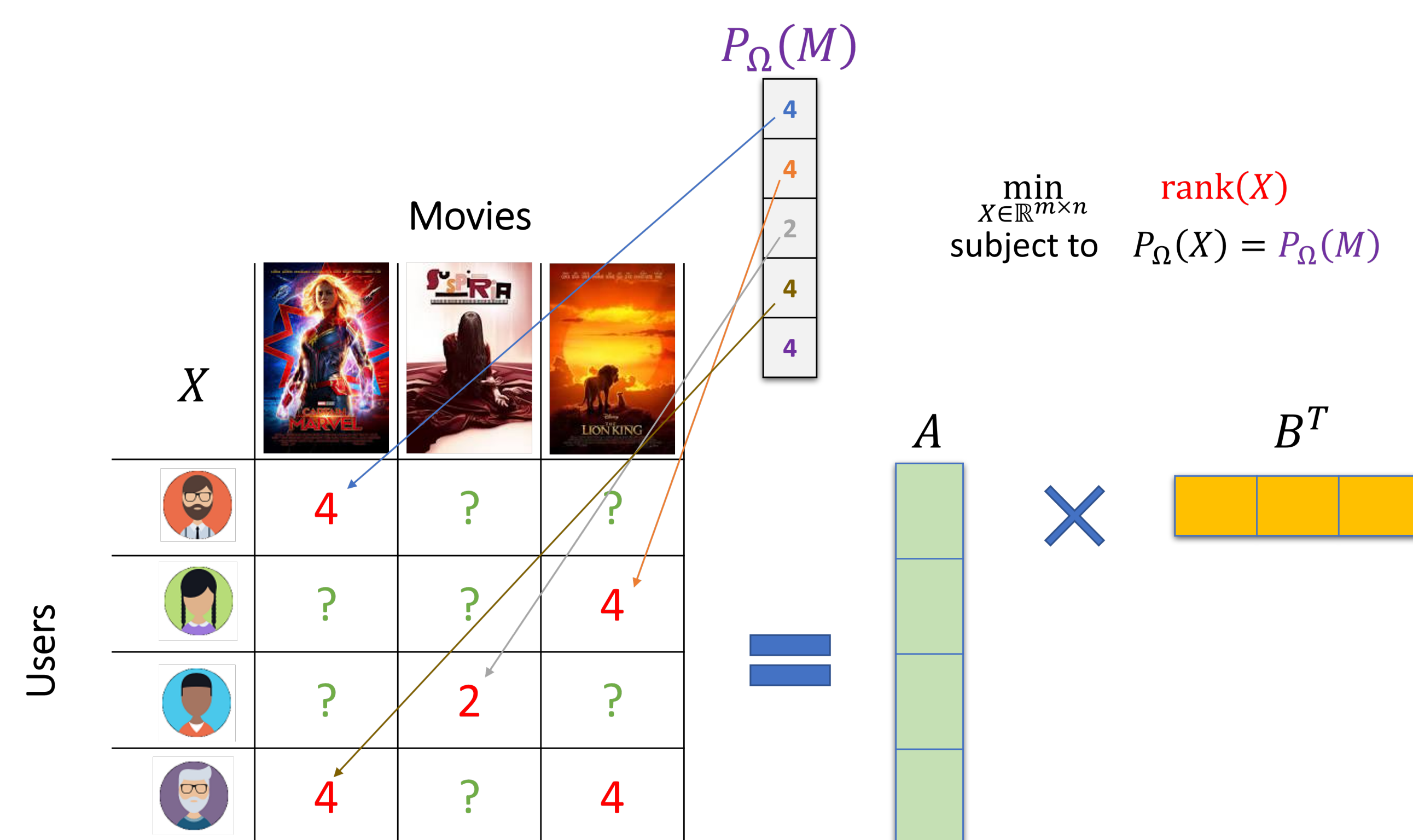
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Matrix Completion Problem (MCP)



- MCP is in general NP-hard
- Low-rank factorization formulation is both *memory and computationally efficient*
- Gradient descent (GD) is a **simple and scalable** method
- Convergence analysis in *non-symmetric* MCP is challenging

Global versus Local Convergence Analysis

Global analysis

- requires assumptions on underlying model in **asymptotic** settings
- is powerful in proving convergence to a **unique global optimum**
- provides **conservative** upper bounds on the linear convergence rate

Local analysis

- identifies the *deterministic* conditions in a **broad range** of settings
- **complementary** to global analysis
- provides an **exact** estimate of the linear rate

Contributions

- ✓ Analyze the **local** convergence of GD for **non-symmetric** MCP
- ✓ Establish the **first-known exact** linear convergence rate
- ✓ Illustrate the **correctness** and **tightness** via numerical simulation

Gradient Descent for Non-Symmetric MCP

Proposed objective function with regularization:

$$\min_{\mathbf{A} \in \mathbb{R}^{m \times r}, \mathbf{B} \in \mathbb{R}^{n \times r}} f(\mathbf{A}, \mathbf{B}) = \frac{1}{2} \|\mathcal{P}_\Omega(\mathbf{A}\mathbf{B}^\top - \mathbf{M})\|_F^2 + \frac{1}{4} \|\mathbf{A}^\top \mathbf{A} - c\mathbf{I}_r\|_F^2$$

- Orthogonality regularization for \mathbf{A} to ensure **uniqueness**
- Scaling factor c to improve the **convergence speed**

Algorithm 1 Factorization-based Gradient Descent

Input: $\mathbf{A}_0, \mathbf{B}_0, \mathcal{P}_\Omega(\mathbf{M}), \eta$

Output: $\{\mathbf{A}_k, \mathbf{B}_k\}$

- 1: for $k = 0, 1, 2, \dots$ do
- 2: $\mathbf{P}_k = \mathcal{P}_\Omega(\mathbf{A}_k \mathbf{B}_k^\top - \mathbf{M})$
- 3: $\mathbf{A}_{k+1} = \mathbf{A}_k - \eta(\mathbf{P}_k \mathbf{B}_k + \mathbf{A}_k(\mathbf{A}_k^\top \mathbf{A}_k - c\mathbf{I}_r))$ ▷ **A**-update
- 4: $\mathbf{B}_{k+1} = \mathbf{B}_k - \eta \mathbf{P}_k^\top \mathbf{A}_k$ ▷ **B**-update

Local Convergence Analysis

Establishing a recursion on the error

- Consider the SVD $\mathbf{M} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^\top = \mathbf{A}_* \mathbf{B}_*^\top$. Define the **error matrix**

$$\mathbf{E}_k = \begin{bmatrix} \mathbf{A}_k \\ \mathbf{B}_k \end{bmatrix} \begin{bmatrix} \mathbf{A}_k^\top & \mathbf{B}_k^\top \end{bmatrix} - \begin{bmatrix} \mathbf{A}_* \\ \mathbf{B}_* \end{bmatrix} \begin{bmatrix} \mathbf{A}_*^\top & \mathbf{B}_*^\top \end{bmatrix} = \begin{bmatrix} \mathbf{E}_k^{AA} & \mathbf{E}_k^{AB} \\ \mathbf{E}_k^{BA} & \mathbf{E}_k^{BB} \end{bmatrix}$$

- Using the \mathbf{A} and \mathbf{B} updates to represent

$$\text{vec}(\mathbf{E}_{k+1}) = \mathbf{Z}(\mathbf{I}_{(m+n)^2} - \eta \mathbf{H}) \mathbf{Z}^\top \text{vec}(\mathbf{E}_k) + \mathcal{O}(\|\mathbf{E}_k\|_F^2) \quad (1)$$

- \mathbf{H} depends *only* on the solution matrix \mathbf{M} and the sampling set Ω
- \mathbf{Z} is a permutation matrix

Integrating structural constraints

- \mathbf{E}_k is the difference between 2 rank- r PSD matrices in $\mathbb{R}^{(m+n) \times (m+n)}$

$$\text{vec}(\mathbf{E}_k) = \mathbf{P}_{\text{sym}} \mathbf{P}_{T_r} \text{vec}(\mathbf{E}_k) + \mathcal{O}(\|\mathbf{E}_k\|_F^2) \quad (2)$$

- \mathbf{P}_{sym} is the projection onto the set of **symmetric matrices**
- \mathbf{P}_{T_r} is the projection onto the *tangent space* of the set of **rank- r matrices**

- Decompose $\mathbf{P}_{\text{sym}} \mathbf{P}_{T_r} = \mathbf{Q}\mathbf{Q}^\top$. Substituting (2) back into (1) yields

$$\mathbf{Q}^\top \text{vec}(\mathbf{E}_{k+1}) = \mathbf{Q}^\top \mathbf{Z}(\mathbf{I}_{(m+n)^2} - \eta \mathbf{H}) \mathbf{Z}^\top \mathbf{Q} \mathbf{Q}^\top \text{vec}(\mathbf{E}_k) + \mathcal{O}(\|\mathbf{E}_k\|_F^2)$$

Convergence of fixed-point iterations

If $\mathbf{Q}^\top \mathbf{Z}(\mathbf{I}_{(m+n)^2} - \eta \mathbf{H}) \mathbf{Z}^\top \mathbf{Q}$ is a **contraction map**, then starting with \mathbf{E}_0 sufficiently small (in norm), we have

$$\|\mathbf{E}_k\|_F \leq C \|\mathbf{E}_0\|_F \cdot \rho^k,$$

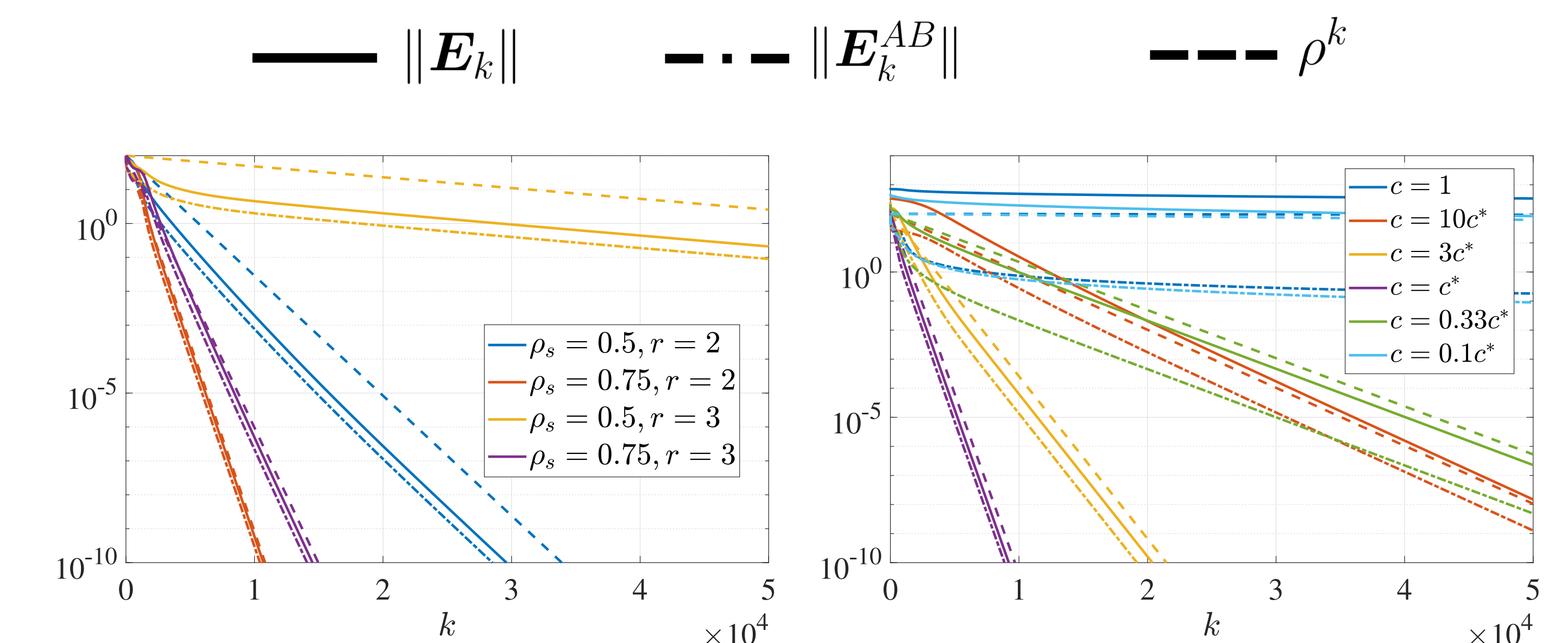
where ρ is the *spectral radius* of $\mathbf{Q}^\top \mathbf{Z}(\mathbf{I}_{(m+n)^2} - \eta \mathbf{H}) \mathbf{Z}^\top \mathbf{Q}$ and $C > 0$ is some numerical constant

Main Theorem

If $\hat{\mathbf{H}} = \mathbf{Q}^\top \mathbf{Z} \mathbf{H} \mathbf{Z}^\top \mathbf{Q}$ is non-singular and $\mathbf{A}_0 \mathbf{B}_0^\top$ is sufficiently close to \mathbf{M} , then Algorithm 1 produces a sequence of matrices $\mathbf{A}_k \mathbf{B}_k^\top$ converging to \mathbf{M} at an **asymptotic linear rate**

$$\rho = \max\{|1 - \eta \lambda_{\max}(\hat{\mathbf{H}})|, |1 - \eta \lambda_{\min}(\hat{\mathbf{H}})|\}$$

Numerical Results



Summary

- (Left) The empirical rate at which $\|\mathbf{E}_k\|_F$ and $\|\mathbf{E}_k^{AB}\|_F$ decrease to zero **matches** that of our **exact analytical rate** ρ^k
- (Right) $c = 1$ results in **slow** convergence since $\|\mathbf{A}\|_F$ and $\|\mathbf{B}\|_F$ are significantly different
- (Right) $c^* = \sqrt{\frac{mn}{r\|\Omega\|}} \|\mathcal{P}_\Omega(\mathbf{M})\|_F$ yields the **fastest** empirical convergence with $\|\mathbf{A}\|_F \approx \|\mathbf{B}\|_F$

More about **exact linear convergence rate analysis** \Rightarrow

